Bayesian Treatment of Incomplete Discrete Data applied to Mutual Information and Feature Selection

Marcus Hutter & Marco Zaffalon



IDSIA

Galleria 2, 6928 Manno (Lugano), Switzerland www.idsia.ch/~{marcus,zaffalon} {marcus,zaffalon}@idsia.ch

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Abstract

Given the joint chances of a pair of random variables one can compute quantities of interest, like the mutual information. The Bayesian treatment of unknown chances involves computing, from a second order prior distribution and the data likelihood, a posterior distribution of the chances. A common treatment of incomplete data is to assume ignorability and determine the chances by the expectation maximization (EM) algorithm. The two different methods above are well established but typically separated. This paper joins the two approaches in the case of Dirichlet priors, and derives efficient approximations for the mean, mode and the (co)variance of the chances and the mutual information. Furthermore, we prove the unimodality of the posterior distribution, whence the important property of convergence of EM to the global maximum in the chosen framework. These results are applied to the problem of selecting features for incremental learning and naive Bayes classification. A fast filter based on the distribution of mutual information is shown to outperform the traditional filter based on empirical mutual information on a number of incomplete real data sets.

Mutual Information (MI)

- Consider two discrete random variables (ι, γ) p_{ij} = joint chance of (i, j), $i \in \{1, ..., r\}$ and $j \in \{1, ..., s\}$ $p_{i+} = \sum_{j} p_{ij}$ = marginal chance of i $p_{+j} = \sum_{i} p_{ij}$ = marginal chance of j
- (In)Dependence often measured by MI

$$0 \le I(\mathbf{p}) = \sum_{ij} \mathbf{p}_{ij} \log \frac{\mathbf{p}_{ij}}{\mathbf{p}_{i+}\mathbf{p}_{+j}}$$

- Also known as cross-entropy or information gain
- Examples
 - Inference of Bayesian nets, classification trees
 - Selection of relevant variables for the task at hand

MI-Based Feature-Selection Filter (F) Lewis, 1992

Classification

- Predicting the *class* value given values of *features*
- Features (or attributes) and class = random variables
- Learning the rule 'features \rightarrow class' from data
- Filters goal: removing irrelevant features
 - More accurate predictions, easier models
- MI-based approach
 - Remove feature ι if class γ does not depend on it: $I(\mathbf{p}) = 0$
 - Or: remove ι if $I(\mathbf{p}) < \mathbf{e}$
 - $e \in \mathfrak{R}^+$ is an arbitrary threshold of relevance

Empirical Mutual Information a common way to use MI in practice

Data (n) \rightarrow contingency table $n_{ij} = \# \text{ of times } (i,j) \text{ occurred}$ $n_{i+} = \sum_{j} n_{ij} = \# \text{ of times } i \text{ occurred}$ $n_{+j} = \sum_{i} n_{ij} = \# \text{ of times } j \text{ occurred}$ $n = \sum_{ij} n_{ij} = \text{ dataset size}$

j∖i	1	2	•••	r
1	<i>n</i> ₁₁	<i>n</i> ₁₂	• • •	n _{1r}
2	n ₂₁	n ₂₂	•••	n _{2r}
÷	:	÷	••••	:
S	n _{s1}	n _{s2}	•••	n _{sr}

- Empirical (sample) probability: $\hat{p}_{ii} = n_{ii} / n$
- Empirical mutual information: $I(\hat{\mathbf{p}})$
- $\hat{\boldsymbol{p}}_{ij} = n_{ij} / n_{ij}$
- Problems of the empirical approach
 - $I(\hat{\mathbf{p}}) = 0$ due to random fluctuations? (finite sample)
 - How to know if it is reliable, e.g. by $P(I > e|\mathbf{n})$?

Incomplete Samples

Missing features/classes

- Missing class: (i,?) \rightarrow n_{i?} = # features i with missing class label
- Missing feature: (?,j) \rightarrow n_{?j} = # classes j with missing feature
- Total sample size $N_{ij} = n_{ij} + n_{i?} + n_{?j}$
- MAR assumption: $\pi_{i?} = \pi_{i+}$, $\pi_{?j} = \pi_{+j}$
 - General case: missing features and class
 - EM + closed-form leading order in N⁻¹ expressions
 - Missing features only
 - Closed-form leading order expressions for Mean and Variance
 - Complexity O(rs)

We Need the Distribution of MI

Bayesian approach

- Prior distribution $p(\mathbf{p})$ for the unknown chances (e.g., Dirichlet)
- Posterior: $p(\mathbf{p}|\mathbf{n}) \propto p(\mathbf{p}) \prod_{ij} \mathbf{p}_{ij}^{n_{ij}} \prod_{i} \mathbf{p}_{i+1}^{n_{ij}} \prod_{j} \mathbf{p}_{j}^{n_{ij}}$
- Posterior probability density of MI:

 $p(I|\mathbf{n}) = \int d(I(\mathbf{p}) - I)p(\mathbf{p}|\mathbf{n})d\mathbf{p}$

- How to compute it?
 - Fitting a curve using mode and approximate variance

Mean and Variance of p and I (missing features only)

Exact mode $\hat{p}_{ij} = \frac{N_{ij}}{N} \frac{n_{ij}}{n_{i+}} = E[p] + O(N^{-1})$ = leading mean
Leading covariance: $Cov_{(ij)(kl)}[p] \cong \frac{1}{N} [r_{ij}d_{ik}d_{jl} - \frac{r_{ij}r_{kl}}{r_{i+}}d_{ik} - \frac{r_{ij}Q_{i?}r_{kl}Q_{k?}}{Q}]$ with $Q_{i?} \coloneqq \frac{r_{i?}}{r_{i?} + r_{i+}}, \quad Q \coloneqq \sum_{i} r_{i+}Q_{i?}, \quad r_{ij} = N\frac{\hat{p}_{ij}^{2}}{n_{ij}}, \quad r_{i?} = N\frac{\hat{p}_{i+}^{2}}{n_{i?}}$ Exact mode = $I(\hat{p}) = E[I] + O(N^{-1})$ = leading order mean Leading variance: $Var[I] \cong \frac{1}{N} [K - J^2 / Q - P], \quad K \coloneqq \sum_{ij} \mathbf{r}_{ij} (\log \frac{\hat{\mathbf{p}}_{ij}}{\hat{\mathbf{p}}_{i+} \hat{\mathbf{p}}_{+j}})^2$ $P \coloneqq \sum_i \frac{J_{i+}^2 Q_{i?}}{\mathbf{r}_{i?}}, \quad J \coloneqq \sum_i J_{i+} Q_{i?}, \quad J_{i+} \coloneqq \sum_{ij} \mathbf{r}_{ij} \log \frac{\hat{\mathbf{p}}_{ij}}{\hat{\mathbf{p}}_{i+} \hat{\mathbf{p}}_{+j}}$

• Missing features & classes: EM converges globally, since $p(\pi|n)$ is unimodal

MI Density Example Graphs (complete sample)





Robust Feature Selection

Filters: two new proposals

- FF: include feature ι iff $P(I > e|\mathbf{n}) > 0.95$
 - (include iff "proven" relevant)
- BF: exclude feature ι iff $P(I \le e|\mathbf{n}) > 0.95$
 - (exclude iff "proven" irrelevant)





Comparing the Filters

Experimental set-up

- Filter (F,FF,BF) + Naive Bayes classifier
- Sequential learning and testing
- Collected measures for each filter
 - Average # of correct predictions (prediction accuracy)
 - Average # of features used

Results on 10 Complete Datasets

of used features

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#	nstances	# Features	Dataset	FF	F	BF
	690	36	Australian	32.6	34.3	35.9
	3196	36	Chess	12.6	18.1	26.1
	653	15	Crx	11.9	13.2	15.0
	1000	17	German-org	5.1	8.8	15.2
	2238	23	Hypothyroid	4.8	8.4	17.1
	3200	24	Led24	13.6	14.0	24.0
	148	18	Lymphography	18.0	18.0	18.0
	5800	8	Shuttle-small	7.1	7.7	8.0
	1101	21611	Spam	123.1	822.0	13127.4
	435	16	Vote	14.0	15.2	16.0

- Accuracies NOT significantly different
 - Except Chess & Spam with FF

Results on 10 Complete Datasets - ctd



FF: Significantly Better Accuracies



Results on 5 Incomplete Data Sets

# Instances	# Features # miss.vals		Dataset	FF	F	BF
226	69	317	Audiology	64.3	68.0	68.7
690	15	67	Crx	9.7	12.6	13.8
368	18	1281	Horse-Colic	11.8	16.1	17.4
3163	23	1980	Hypothyroidloss	4.3	8.3	13.2
683	35	2337	Soybean-large	34.2	35.0	35.0

Percentages of used features





Conclusions

- Expressions for several moments of π and MI distribution even for incomplete categorical data
 - The distribution can be approximated well
 - Safer inferences, same computational complexity of empirical MI
 - Why not to use it?

. . .

- Robust feature selection shows power of MI distribution
 - FF outperforms traditional filter F
- Many useful applications possible
 - Inference of Bayesian nets
 - Inference of classification trees