

# Convergence of Discrete MDL for Sequential Prediction

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# Overview

- Sequential online prediction in a Bayesian framework
- No i.i.d. assumption!!!
- Applies to classification and to regression
- Applies to Universal Prediction in the sense of AIT
- We will obtain strong asymptotic assertions
- ... and also (weak) loss bounds



# Rough Problem Setup

- Given an initial part  $x = x_{1:t}$  of a sequence, predict the next symbol  $x_{t+1}$
- Examples:
  - $x = 01010101010101$
  - $x = 1100100100001111110110101010001000100001$
  - $x = 0001111001010010001111110110101001001111$



# (Semi)Measures

- This is a "binary talk", but everything also works for arbitrary alphabet!
- Let  $\mathbb{B} = \{0, 1\}$ ,  $\mathbb{B}^\infty = \{\text{all binary sequences}\}$
- $\epsilon$  is the empty string
- A *measure*  $\mu$  is a function  $\mu : \mathbb{B}^* \rightarrow [0, 1]$  s.t.

$$\mu(\epsilon) = 1 \text{ and } \mu(x) = \mu(x0) + \mu(x1) \text{ for all } x$$

- A *semimeasure*  $\nu$  has

$$\nu(\epsilon) \leq 1 \text{ and } \nu(x) \geq \nu(x0) + \nu(x1) \text{ for all } x$$



# Examples: (Semi)Measures

- $\lambda(x) = 2^{-length(x)}$  is the uniform measure
- $\mu_1(111...1) = 1$  and  $\mu_1(x) = 0$  if  $x$  contains at least one 0, is a deterministic measure
- $M_U(x) =$  the probability that some universal Turing machine (UTM)  $U$  outputs a string starting with  $x$  when the input is random coin flips
- The latter is a semimeasure, not a measure, since  $U$  does not halt on each input!
- Binary classification:  $\mu(1|z)$  is i.i.d. given some input  $z$  (conditionalized measure)



# Classes of (Semi)Measures

- Let  $\mathcal{C}$  be a *countable* class of (semi)measures
- Each  $\nu \in \mathcal{C}$  is assigned a *prior weight*  $w_\nu > 0$
- Kraft inequality:  $\sum_{\nu \in \mathcal{C}} w_\nu \leq 1$
- Universal setup:  $\mathcal{C} = \mathcal{M} \cong$  all programs on a UTM  $U$
- $w_\nu = 2^{-K(\nu)}$  where  $K(\nu)$  is the *prefix Kolmogorov Complexity* of  $\nu$ , i.e. the length of the shortest self-delimiting program defining  $\nu$



# Assumptions

- We make *no probabilistic* assumption on  $\mathcal{C}$
- We show bounds for given *true distribution*  $\mu$
- which is a *measure* (not a semimeasure)
- *and assumed to be in  $\mathcal{C}$*
- Thus, bounds depend on the complexity (or prior weight  $w_\mu$ ) of the true distribution
- Occam's razor
- priors correspond to regularization



# Bayes Mixtures

- We denote a Bayes mixture by  $\xi$
- Given observation  $x$  and a countable class together with weights  $(w_\nu)$ , the  $\xi$ -prediction is

$$\xi(a|x) = \frac{\sum_\nu w_\nu \nu(xa)}{\sum_\nu w_\nu \nu(x)}$$

for  $a \in \{0, 1\}$ .

- $\xi$  is semimeasure
- “Committee of all models”





# Minimum Description Length

- Minimum Description Length (MDL) estimator

$$\nu^x = \arg \max \{w_\nu \nu(x)\}$$

$$\varrho(x) = \max \{w_\nu \nu(x)\}$$

- $\nu^x$  is *maximizing element*
- $-\log \varrho(x) = \min \{-\log w_\nu - \log \nu(x)\}$
- $-\log w_\nu \leftrightarrow$  code of the model
- $-\log \nu(x) \leftrightarrow$  code of data given



# Prediction using MDL

- Dynamic MDL predictor:  $\varrho(a|x) = \frac{\varrho(xa)}{\varrho(x)}$   
not a semimeasure!
- Normalized dynamic MDL:  $\varrho(a|x) = \frac{\varrho(xa)}{\varrho(x0)+\varrho(x1)}$   
measure  
search new model for each next symbol
- Static MDL predictor:  $\varrho^x(a|x) = \frac{\nu^x(xa)}{\nu^x(x)}$   
(semi)measure  
find best model and use this for prediction
- $\Rightarrow$  Static MDL is computationally more efficient



# Bayes Mixture Predictions

- **Theorem** (Solomonoff): Let  $\mu \in \mathcal{C}$  be a measure, then

$$\sum_{t=0}^{\infty} \mathbf{E} \sum_{a \in \{0,1\}} (\mu(a|x_{1:t}) - \xi(a|x_{1:t}))^2 \leq \ln(w_{\mu}^{-1})$$

- $\Rightarrow$  The posteriors *almost surely* converge to the true probabilities *fast*
- Universal setup:  $\mu$  must be a computable measure
- This requirement is (philosophically) very weak



# Proof of Solomonoff's Theorem

$$\begin{aligned}
 & \sum_{t=0}^T \mathbf{E} \sum_{a \in \{0,1\}} (\mu(a|x_{1:t}) - \xi(a|x_{1:t}))^2 \\
 & \leq \sum_{t=0}^T \mathbf{E} \sum_{a \in \{0,1\}} \mu(a|x_{1:t}) \ln \frac{\mu(a|x_{1:t})}{\xi(a|x_{1:t})} = \sum_{t=0}^T \mathbf{E} \ln \frac{\mu(x_t|x_{1:t})}{\xi(x_t|x_{1:t})} \\
 & = \mathbf{E} \ln \left( \prod_{t=0}^T \frac{\mu(x_t|x_{1:t})}{\xi(x_t|x_{1:t})} \right) = \mathbf{E} \ln \frac{\mu(x_{1:T+1})}{\xi(x_{1:T+1})} \leq \ln w_\mu^{-1}
 \end{aligned}$$

## Lemma:

The quadratic distance is bounded by the relative entropy.

## Observation:

$x$  dominates  $\mu$ , i.e.  $x(x) \geq w_\mu \mu(x)$  for all  $x$



# MDL: Main Theorem

**Theorem:**  $\mu \in \mathcal{C}$  measure, then

$$(i) \quad \sum_{t=0}^{\infty} \mathbf{E} \sum_{a \in \{0,1\}} \left( \mu(a|x_{1:t}) - \varrho_{\text{norm}}(a|x_{1:t}) \right)^2 \leq \ln w_{\mu}^{-1} + w_{\mu}^{-1},$$

normalized dynamic

$$(ii) \quad \sum_{t=0}^{\infty} \mathbf{E} \sum_{a \in \{0,1\}} \left( \mu(a|x_{1:t}) - \varrho(a|x_{1:t}) \right)^2 \leq 8 \cdot w_{\mu}^{-1},$$

dynamic

$$(iii) \quad \sum_{t=0}^{\infty} \mathbf{E} \sum_{a \in \{0,1\}} \left( \mu(a|x_{1:t}) - \varrho^{x_{1:t}}(a|x_{1:t}) \right)^2 \leq 21 \cdot w_{\mu}^{-1}$$

static

$\Rightarrow$  The posteriors *almost surely* converge to the true probabilities, but convergence is *slow* in general



# Proof Idea

- For  $\varrho_{\text{norm}}$ :
  - use relative entropy bound
  - decompose  $\varrho_{\text{norm}}$  in  $\varrho$  and normalizer
  - $\varrho$ -contribution bounded by  $\ln w_{\mu}^{-1}$
  - normalizer contribution bounded by  $w_{\mu}^{-1}$
- Then bound the cumulative absolute difference  $|\varrho - \varrho_{\text{norm}}|$  by  $2w_{\mu}^{-1}$
- Finally bound the cumulative absolute difference  $|\varrho^x - \varrho|$  by  $3w_{\mu}^{-1}$
- square distances may be chained



# Loss Bounds

- **Theorem** (Hutter):  $\mu \in \mathcal{C}$  measure  $\Rightarrow$

$$L^\xi(T) \leq L^\mu(T) + 2\sqrt{L^\mu(T) \ln w_\mu^{-1}} + 2 \ln w_\mu^{-1}$$

for 0/1 los and arbitrary loss

- **Corollary:** For arbitrary loss,

$$L^{\varrho_{\text{norm}}}(T) \leq L^\mu(T) + O(\sqrt{L^\mu(T)w_\mu^{-1}}) + O(w_\mu^{-1})$$



# Loss Bounds

- **Corollary:** For 0/1 loss,

$$L^{\varrho}(T) \leq L^{\mu}(T) + O(\sqrt{L^{\mu}(T)w_{\mu}^{-1}}) + O(w_{\mu}^{-1})$$

$$L^{\varrho^x}(T) \leq L^{\mu}(T) + O(\sqrt{L^{\mu}(T)w_{\mu}^{-1}}) + O(w_{\mu}^{-1})$$

- Arbitrary loss open!
- Compare to prediction with expert advice: *worst-case* loss for *individual* sequences

$$L^{PEA}(T) \leq L^{\mu}(T) + 2\sqrt{2L^{\mu}(T) \ln w_{\mu}^{-1}} + O(\ln w_{\mu}^{-1})$$





# Exponential Bounds are Sharp

- MDL bound exponentially worse than Bayes mixture
- This bound is sharp! Example  $\nu_1, \dots, \nu_7, \nu_8 = \mu$   
*deterministic*,

$$\begin{array}{l}
 \nu_1 : 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \dots, \quad w_1 = \frac{1}{8} \\
 \nu_2 : 1 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \dots, \quad w_2 = \frac{1}{8} \\
 \nu_3 : 1 \quad 1 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \dots, \quad w_3 = \frac{1}{8} \\
 \nu_4 : 1 \quad 1 \quad 1 \quad 0 \quad 0 \quad 0 \quad 0 \dots, \quad w_4 = \frac{1}{8} \\
 \nu_5 : 1 \quad 1 \quad 1 \quad 1 \quad 0 \quad 0 \quad 0 \dots, \quad w_5 = \frac{1}{8} \\
 \nu_6 : 1 \quad 1 \quad 1 \quad 1 \quad 1 \quad 0 \quad 0 \dots, \quad w_6 = \frac{1}{8} \\
 \nu_7 : 1 \quad 1 \quad 1 \quad 1 \quad 1 \quad 1 \quad 0 \dots, \quad w_7 = \frac{1}{8} \\
 \mu = \nu_8 : 1 \quad 1 \quad 1 \quad 1 \quad 1 \quad 1 \quad 1 \dots, \quad w_8 = \frac{1}{8}
 \end{array}$$



# Exponential Bounds are Sharp

- Then normalized dynamic MDL predicts probability of  $\frac{1}{2}$  for  $t = 1, \dots, 7$
- $\rightarrow$  cumulative error =  $O(w_\mu^{-1})$
- The bound is even sharp if  $\mathcal{C}$  contains only Bernoulli distributions!
- But there under additional mild conditions, a good bound holds



# Hybrid MDL predictions

- Hybrid MDL predictor:  $Q^{hybrid}(a|x) = \frac{\nu^{xa}(xa)}{\nu^x(x)}$
- “Dynamic MDL but drop weights”
- Predictive properties? Poorer!
- Only converges if the maximizing element *stabilizes*
- This happens almost surely if
  - all (semi)measures in  $\mathcal{C}$  are independent of the past (factorizable)
  - $\mu$  is uniformly stochastic, i.e. in each time step either deterministic or noisy with at least a certain amplitude



# Complexity and Randomness

Universal case:  $\mathcal{C} = \mathcal{M}$ , and  $\tilde{\mathcal{C}}$  is  $\mathcal{C}$  restricted to computable measures

$$\Rightarrow 2^{Km(x)} \stackrel{\times}{=} \tilde{\rho}(x) \leq^{\times} \tilde{\xi}(x) \leq^{\times} \rho(x) \stackrel{\times}{=} \xi(x) \stackrel{\times}{=} M(x)$$

Gács:  ~~$\stackrel{\times}{=}$~~   $\Rightarrow$  which inequality is proper?

$\Rightarrow$  all quantities define Martin-Löf randomness by  $f(x_{1:n}) \leq C\mu(x_{1:n})$  for all  $n$  and some  $C$



# Further Open Problems

- Between MDL and Bayes mixture?
- Active Learning?
- Other ideas?
  
- That's it, thank you!